ESTIMATION OF THE PARAMETERS OF A BIVARIATE NORMAL POPULATION FROM TRUNCATED SAMPLES

by

WM. JACKSON HALL

Institute of Statistics, University of North Carolina

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Introduction and summary. Maximum likelihood estimates of the parameters of a bivariate normal distribution are obtained for a sample in which only those observations falling in a specific region can be measured, all other observations being called "unmeasured observations". Two cases are treated, the number of unmeasured observations being unknown (Case I) or known (Case II). Explicit expressions are obtained when the region of truncation is a rectangle or an infinite strip. The asymptotic covariance matrix is obtained simultaneously with the solution.

We denote the bivariate normal density function with parameters $\mu_x, \sigma_x, \mu_y, \sigma_y$, and $\rho$ (sometimes denoted $\lambda_1, \lambda_2, \lambda_3, \lambda_4, \lambda_5$ for convenience) by $\varphi(x, y)$. Then, in Case I, the likelihood of a sample of $n$ independent observations all in a region $R$ is

$$\frac{1}{p^n} \prod_{i=1}^{n} \varphi(x_i, y_i)$$

where

$$p = \Pr \left( (x, y) \text{ in } R \right) = \int_R \varphi(x, y) \, dx \, dy ;$$

and, in Case II, the likelihood of a sample of $N$ independent observations of which $n$ observations occur in $R$ and $N-n$ elsewhere is
\[\binom{n}{M} (1-p)^{N-n} \prod_{i=1}^{n} \phi(x_i, y_i)\]

The partial derivative of the logarithmic likelihood, \(L\), with respect to one of the parameters, say \(\lambda\), is

\[
\frac{\partial L}{\partial \lambda} = -f(n,p) \frac{\partial \phi}{\partial \lambda} + \sum_{i=1}^{n} \frac{\partial}{\partial \lambda} \log \phi(x_i, y_i)
\]

where \(f(n,p) = n/p\) in Case I and \(f(n,p) = (N-n)/(1-p)\) in Case II. To obtain the maximum likelihood estimates, all five partial derivatives are equated to zero and solved for the unknown parameters.

**Iterative solution of the maximum likelihood equations.** To solve the five estimating equations simultaneously, we propose a Newton iterative procedure. Choosing an initial trial solution, we approximate the system of equations by a linear system using the linear terms in a Taylor series expansion. Thus

\[
0 = \frac{\partial L}{\partial \lambda} \cdot (\frac{\partial L}{\partial \lambda})^{(1)} + \sum_{i=1}^{5} \left( \frac{\partial^2 L}{\partial \lambda_i \partial \lambda_j} \right)^{(1)} (\lambda_i - \lambda_j^{(1)}) \quad (j=1, \ldots, 5)
\]

where a subscript \((1)\) denotes evaluation at the first trial point and a superscript \((1)\) denotes the first trial value. In matrix notation we have
\[
\ell^{(1)} = \lambda^{(1)} d^{(1)}
\]

where \( \ell \) is the (column) vector with elements \( \frac{\partial L}{\partial \lambda_j} \) (\( j = 1, \ldots, 5 \)), \( d^{(1)} \) is the (column) vector with elements \( \lambda - \lambda_j^{(1)} \), and

\[
\Lambda = (a_{ij}) = \left( -\frac{\partial^2 L}{\partial \lambda_i \partial \lambda_j} \right).
\]

Second trial values are obtained from the first from

\[
d^{(1)} = \Lambda^{-1} \ell^{(1)}
\]

(assuming \( \Lambda^{(1)} \) non-singular), and by substituting these values for the initial ones further estimates are obtained, and so on until stability is reached. (It may not be necessary to recalculate the \( \Lambda \) matrix at each step if its elements are sufficiently stationary. When it is recalculated, its inverse may be obtained quickly by iteration.)

**Precision of Estimates.** The asymptotic covariance matrix is the inverse of the matrix with elements \( -\frac{\partial^2 L}{\partial \lambda_i \partial \lambda_j} \), and thus may be estimated by \( \Lambda^{-1} \). This estimate is obtained simultaneously with the solution of the estimating equations.
Rectangular truncation. Here we develop explicitly the estimating equations for a rectangularly truncated population. Let the region $R$ be a rectangle, bounded by the lines $x = h_1$, $x = h_2$, $y = k_1$, $y = k_2$ ($h_1 < h_2$, $k_1 < k_2$). Then

$$p = \int_{h_1}^{h_2} \int_{k_1}^{k_2} \phi(x, y) \, dx \, dy.$$

Now $\phi(x, y)$ may be expressed as a power series in $\rho$ with Hermite functions as coefficients

$$\phi(x, y) = \frac{1}{\sigma_x \sigma_y} \sum_{v=0}^{\infty} \frac{\rho^v}{v!} c_v \left( \frac{x-h}{\sigma_x} \right) c_v \left( \frac{y-k}{\sigma_y} \right)$$

where

$$c_v(t) = (-1)^v \frac{1}{\sqrt{2\pi}} \frac{d^v}{dt^v} e^{-t^2/2} \quad (v=1, 2, \ldots)$$

$$c_0(t) = \frac{1}{\sqrt{2\pi}} e^{-t^2/2}.$$

(See R. A. Fisher's introduction, pp.xxvi-xxviii, [2].) For negative subscripts, the Hermite functions are defined by the two following relations:

$$c_{-1}(t) = 1 - \int_{-\infty}^{t} \frac{1}{\sqrt{2\pi}} e^{-x^2/2} \, dx.$$
t G_v(t) = \nu G_{v-1}(t) + G_{v+1}(t).

Since the series in $p$ converges uniformly in x and y, and since \( \int G_v(t) \, dt = -G_{v-1}(t) \), we have

\[
p = \begin{pmatrix} \eta_2 \\ \xi_2 \end{pmatrix} \sum_{v=0}^{\infty} \frac{\rho_v}{v!} \begin{pmatrix} G_v(x) \\ G_v(y) \end{pmatrix} \, dx \, dy
\]

\[
= \sum_{v=0}^{\infty} \frac{\rho_v}{v!} \begin{pmatrix} \xi_2 \\ \eta_2 \end{pmatrix} \begin{pmatrix} G_v(x) \\ G_v(y) \end{pmatrix} \, dy
\]

\[
= \Sigma_{0,0}
\]

where

\[
\gamma_i = \frac{h_i - \mu_x}{\sigma_x} \quad \eta_i = \frac{h_i - \mu_y}{\sigma_y} \quad (i=1,2)
\]

and

\[
\Sigma_{r,s} = \sum_{v=0}^{\infty} \frac{\rho_v}{v!} / G_{v+r-1}(\xi_1) - G_{v+r-1}(\xi_2) / G_{v+s-1}(\eta_1) - G_{v+s-1}(\eta_2) .
\]

After calculating the derivatives of the $\Sigma_{r,s}$ function, we obtain the following derivatives:
TABLES OF PARTIALLY BALANCED DESIGNS WITH TWO ASSOCIATE CLASSES

By R. C. Bose, W. H. Clatworthy and S. S. Shrikhande

(Inst. of Stat. Mimeo. Series No. 77)

Name

Date
\frac{\partial p}{\partial \mu_x} = \frac{1}{\sigma_x} \Sigma_{1,0} \\

(1) \\
\frac{\partial p}{\partial \sigma_x} = \frac{1}{\sigma_x} \left( \rho \Sigma_{1,1}^1 + \Sigma_{2,0} \right) \\
\frac{\partial p}{\partial \rho} = \Sigma_{1,1} \\

\frac{\partial^2 p}{\partial \mu_x^2} = \frac{1}{2} \Sigma_{2,0} \\

\frac{\partial^2 p}{\partial \mu_x \partial \sigma_x} = \frac{1}{2} \sigma_x \left( \rho \Sigma_{2,1}^1 + \Sigma_{3,0} \right) \\
\frac{\partial^2 p}{\partial \mu_x \partial \mu_y} = \frac{1}{\sigma_x \sigma_y} \Sigma_{1,1} \\
\frac{\partial^2 p}{\partial \mu_x \partial \sigma_y} = \frac{1}{\sigma_x \sigma_y} \left( \rho \Sigma_{2,1}^1 + \Sigma_{1,2} \right) \\
\frac{\partial^2 p}{\partial \mu_x \partial \rho} = \frac{1}{\sigma_x} \Sigma_{2,1} 

(2)
\[
\frac{\partial^2 p}{\partial \sigma_x^2} = \frac{1}{\sigma_x^2} (\Sigma_{4,0} + 2 \rho \Sigma_{3,1} + \rho^2 \Sigma_{2,2} + \Sigma_{2,0})
\]

\[
\frac{\partial^2 p}{\partial \sigma_x \partial \sigma_y} = \frac{1}{\sigma_x \sigma_y} \int (1 + \rho^2) \Sigma_{2,2} + \rho (\Sigma_{3,1} + \Sigma_{1,3} + \Sigma_{1,1})
\]

\[
\frac{\partial^2 p}{\partial x \partial p} = \frac{1}{\sigma_x} (\rho \Sigma_{2,2} + \Sigma_{3,1})
\]

\[
\frac{\partial^2 p}{\partial p^2} = \Sigma_{2,2}.
\]

all others being obtained by symmetry. (The interchange of \(x\) and \(y\) requires the interchange of the order of the subscripts on the \(\Sigma_{r,s}\) functions.)

In Case I,

\[(3) \quad \frac{\partial}{\partial \sigma} f(n,p) = -\frac{n}{p^2}.\]

and in Case II,

\[(4) \quad \frac{\partial}{\partial p} f(n,p) = (n-n)/(1-p)^2.\]

Calculating the derivatives of \(\log \phi(x,y)\), we find...
\[ -8 - \]

\[
\sum_{i=1}^{n} \frac{\partial}{\partial x_i} \log \phi(x_i, y_i) = -\frac{n}{\sigma_x (1-\rho^2)} \left( \rho m_{01} - m_{10} \right)
\]

\[ \text{(5)} \]

\[
\sum \frac{\partial}{\partial x} \log \phi = -\frac{n}{\sigma_x (1-\rho^2)} \left( 1 - \rho^2 + \rho m_{11} - m_{20} \right)
\]

\[
\sum \frac{\partial}{\partial \rho} \log \phi = -\frac{n}{(1-\rho^2)^2} \left( \rho (m_{20} + m_{02} - 1 + \rho^2) - (1 + \rho^2) m_{11} \right)
\]

\[ \text{\[6\]} \]

\[
\sum \frac{\partial^2}{\partial x_i^2} \log \phi(x_i, y_i) = -\frac{n}{\sigma_x^2 (1-\rho^2)}
\]

\[
\sum \frac{\partial^2}{\partial x_i \partial y_j} \log \phi = -\frac{n}{\sigma_x^2 (1-\rho^2)} \left( 2m_{10} - \rho m_{01} \right)
\]

\[
\sum \frac{\partial^2}{\partial x_i \partial y_j} \log \phi = \frac{n \rho}{\sigma_x \sigma_y (1-\rho^2)}
\]

\[
\sum \frac{\partial^2}{\partial y_j^2} \log \phi = \frac{n \rho m_{01}}{\sigma_x \sigma_y (1-\rho^2)}
\]

\[
\sum \frac{\partial^2}{\partial x_i \partial \rho} \log \phi = -\frac{n}{\sigma_x (1-\rho^2)^2} \left( 1 + \rho^2 \right) m_{01} - 2 \rho m_{10} m_{11}
\]
\[
\begin{align*}
\sum \frac{\partial^2}{\partial \sigma_x^2} \log \phi &= -\frac{n}{\sigma_x^2 (1-\rho^2)} (3m_{20} - 2\rho m_{11} - 1 + \rho^2) \\
\sum \frac{\partial^2}{\partial \sigma_x \partial \gamma} \log \phi &= -\frac{n\rho m_{11}}{\sigma_x \sigma_y (1-\rho^2)} \\
\sum \frac{\partial^2}{\partial \sigma_x \partial \rho} \log \phi &= -\frac{n}{\sigma_x (1-\rho^2)} \sqrt{(1 + \rho^2)} m_{11} - 2\rho m_{20} \\
\sum \frac{\partial^2}{\partial \rho^2} \log \phi &= \frac{n}{(1-\rho^2)^3} \sqrt{(1 + 3\rho^2)(m_{20} + m_{02})} \\
&\quad - 2\rho (3 + \rho^2) m_{11} - (1-\rho^4) \\
\end{align*}
\]

all others being obtained by symmetry; we have denoted

\[
m_{rs} = \frac{1}{n} \sum_{i=1}^{n} \frac{(x_i - \mu_x)^r}{\sigma_x} \left( \frac{y_i - \mu_y}{\sigma_y} \right)^s \quad (r,s = 0,1,2).
\]

Using (1) and (5), we may now calculate the elements of the \( \gamma \) vector:

\[
\frac{\partial L}{\partial \gamma} = -f(n,p) \frac{\partial \gamma}{\partial \gamma} + \sum_{i=1}^{n} \frac{\partial}{\partial \gamma} \log \phi(x_i, y_i)
\]

and using (1), (2), (3), (4), and (6), we may calculate the elements of the

A matrix.
\begin{equation}
\frac{\partial^2 l}{\partial \lambda_j \partial \lambda_k} = f(n,p) \frac{\partial^2 p}{\partial \lambda_j \partial \lambda_k} + \frac{af}{\partial p} \frac{\partial p}{\partial \lambda_j} \frac{\partial p}{\partial \lambda_k} - \sum_{i=1}^{n} \frac{\partial^2}{\partial \lambda_j \partial \lambda_k} \log \phi(x_i,y_i).
\end{equation}

(The required \( \gamma_{r,s} \) functions may be computed from tables of the tetrachoric functions \( \int_{-\infty}^{\infty} \), using the relation
\[ \sqrt{v} \int_{-\infty}^{v} \gamma(t) = G(v) \text{.} \]

The estimates for truncation over an infinite quarter-plane may be obtained by letting one of the \( h_i \)'s and one of the \( k_i \)'s in the discussion above \( \gamma_0 \) to \( \pm \infty \).

Initial estimates may be obtained by approximating the region \( R \) by an infinite strip and using the linear truncation estimation method which follows.

**Linear truncation.** We shall consider independently the estimation problem when the region \( R \) is an infinite strip, bounded by \( x = h_1 \) and \( x = h_2 \) \((h_1 < h_2)\). Here, we shall distinguish three cases: (I) the number of unmeasured observations is unknown, (II) the numbers of unmeasured observations in each truncated half-plane are known (say \( n_1 \) observations in \( R_1 = \int_{-\infty}^{h_1} \), and \( n_2 \) in \( R_2 = \int_{h_2}^{\infty} \)), \( n_1 + n_2 = N-n \), and (III) only the total number \( N-n \) of unmeasured observations is known.

Now the marginal distribution of \( x \) is independent of \( \mu_y \), \( \sigma_y \), and \( \rho \), and is simply a truncated univariate normal distribution. Thus, in all three cases, \( \mu_x \) and \( \sigma_x \) may be estimated by the methods of A. C. Cohen for truncated univariate normal distributions, the three cases above corresponding to the three cases enumerated by Cohen.

The likelihood functions in the three cases are:
\( \left\{ \begin{array}{l} (I) \quad \frac{1}{p^n} \prod_{i=1}^{n} \phi(x_i, y_i) \\
(II) \quad k_1 p_1^{n_1} p_2^{n_2} \prod_{i=1}^{n} \phi(x_i, y_i) \\
(III) \quad k_2 (1-p)^{N-n} \prod_{i=1}^{n} \phi(x_i, y_i) \end{array} \right. \)

where

\[ p = \Pr \left[ (x, y) \in R_1 \right] = \Phi \left( \frac{h - \mu_x}{\sigma_x} \right) - \Phi \left( \frac{h - \mu_y}{\sigma_y} \right) \]

\[ p_1 = \Pr \left[ (x, y) \in R_2 \right] = \Phi \left( \frac{h - \mu_x}{\sigma_x} \right) \]

\[ p_2 = \Pr \left[ (x, y) \in R_3 \right] = 1 - \Phi \left( \frac{h - \mu_y}{\sigma_y} \right) \]

and

\[ \Phi(t) = \int_{-\infty}^{t} \frac{1}{\sqrt{2\pi}} e^{-t^2/2} dt \]

\( k_1 \) and \( k_2 \) are constants. Since \( p, p_1, \) and \( p_2 \) are all independent of \( \mu_y, \sigma_y, \) and \( \rho, \) the maximum likelihood equations for these three parameters will be the same in all three cases; namely, from (5) and (9),

\[ \frac{\partial L}{\partial \mu_y} = -\frac{n}{\sigma_y (1-\rho^2)} \left( \rho m_{10} - m_{01} \right) = 0 \]
where \( L \) denotes the logarithmic likelihood, \( m_{rs} \) being defined by (7). Having obtained estimates of \( \mu_x \) and \( \sigma_x \) by Cohen's method, these three equations may be solved for estimates of \( \mu_y, \sigma_y, \) and \( \rho \), yielding (after some algebraic manipulation):

\[
\mu_y = \frac{(m_{11}' - m_{01}' \mu_x)(m_{10}' - \mu_x) - m_{01}'(m_{20}' - 2m_{10}' \mu_x + \mu_x^2)}{(m_{10}' - \mu_x)^2 - (m_{20}' - 2m_{10}' \mu_x + \mu_x^2)}
\]

\( (10) \quad \sigma_y^2 = m_{02}' - 2m_{01}' \mu_y + \mu_y^2 + \frac{(m_{01}' - \mu_y)^2}{(m_{10}' - \mu_x)} \int \sigma_x^2 - (m_{20}' - 2m_{10}' \mu_x + \mu_x^2) \right]
\]

\( (11) \quad \rho = \frac{\sigma_x m_{01}' - \mu_y}{\sigma_y m_{10}' - \mu_x} \]

where \( m_{rs}' \) denotes sample moments about the origin. If \( \mu_x = m_{10}' \), then we substitute

\[
\frac{m_{11}' - m_{10}' m_{01}'}{m_{20}' - m_{10}'} \quad \text{for} \quad \frac{m_{01}' - \mu_y}{m_{10}' - \mu_x}
\]
in equations (10) and (11).

Since the estimates of \( \mu_x \) and \( \sigma_x \) are independent of \( \mu_y \), \( \sigma_y \), and \( \rho \), we find that the A matrix is now the direct sum of two sub-matrices, and likewise for its inverse. The first inverse sub-matrix (corresponding to \( \mu_x \) and \( \sigma_x \)) is given by Cohen [4], the second may be obtained by inverting the matrix whose elements are given by (8).

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REFERENCES


