

¹ *Harvard University. Arrow's work was sponsored in part by the Office of Naval Research under grant number N00014-67A-0298-0019 (NRO47-004).*

² *University of North Carolina at Chapel Hill. The work of Gould and Howe was sponsored in part by the Office of Naval Research under grant number N000-14-67-A-0321-0003 (NRO47-096).*

A GENERAL SADDLE POINT RESULT FOR CONSTRAINED OPTIMIZATION

by

K.J. Arrow¹, F.J. Gould², S.M. Howe²

*Department of Statistics
University of North Carolina at Chapel Hill*

Institute of Statistics Mimeo Series No. 774

September, 1971

A GENERAL SADDLE POINT RESULT FOR CONSTRAINED OPTIMIZATION

by

K. J. Arrow¹, F. J. Gould², S. M. Howe²

I. INTRODUCTION

In the context of nonlinear programming theory, the existence of a saddle point of the Lagrangian function is known to be heavily dependent upon convexity properties of the underlying problem. In particular, for a concave program satisfying the Slater condition, with a solution x^* , there is a u^* such that x^*, u^* is a saddle point of the Lagrangian function. In 1956, motivated by game theoretical and economic implications, Arrow and Hurwicz demonstrated that the concavity assumptions could be relaxed via a modified Lagrangian approach [1]. The results in this 1956 paper were presented in terms of a specific modified Lagrangian formulation. In 1958, in a discussion of gradient methods, Arrow and Solow presented additional saddle point results in terms of a different modified Lagrangian function [2]. Another specific result along the same lines was presented by Gould and Howe in 1971 [4].

In this work, we both generalize and simplify the above presentations. Conditions will be given under which, for a nonconcave (as well as concave) program, a quite general function P will possess a saddle point corresponding

¹ Harvard University. Arrow's work was sponsored in part by the Office of Naval Research under grant number N00014-67A-0298-0019 (NRO47-004).

² University of North Carolina at Chapel Hill. The work of Gould and Howe was sponsored in part by the Office of Naval Research under grant number N000-14-67-A-0321-0003 (NRO47-096).

to the program solution. Specific realizations of the P function will be the modified Lagrangian expressions discussed by the above mentioned authors.

II. REDUCTION TO AN UNCONSTRAINED PROBLEM

We formulate the nonlinear program with both equality and inequality constraints:

$$(P) \quad \max_{x \in R^n} f(x), \text{ subject to } \begin{aligned} g_i(x) &\leq 0, \quad i = 1, \dots, m \\ h_j(x) &= 0, \quad j = 1, \dots, p. \end{aligned}$$

Throughout the paper it is assumed that all functions in (P) are twice differentiable.

Corresponding to the inequality constraints (the correspondence will be clear from the P function formulation) let $\lambda(\xi, \eta, \alpha): R \times R_+ \times R_+ \rightarrow R$ be a multiplier function having second partial derivatives with respect to the first argument¹, where we employ the notation $\partial\lambda/\partial\xi = \lambda_1$, $\partial^2\lambda/\partial\xi^2 = \lambda_{11}$. Impose the following properties on λ

- (i) for any $\alpha > 0$ $\lambda_1(0, \eta, \alpha) = \eta$ for every $\eta \geq 0$
- (ii) for any $\alpha > 0$ $\lambda_1(\xi, 0, \alpha) = 0$ for every $\xi < 0$
- (iii) for each fixed $\eta > 0$ $\lambda_{11}(0, \eta, \alpha) \rightarrow \infty$ as $\alpha \rightarrow \infty$.

Note: (ii) implies that, for any $\alpha > 0$, $\xi < 0$, $\lambda_{11}(\xi, 0, \alpha) = 0$.

Corresponding to the equality constraints let $\phi(\xi, \eta, \alpha): R \times R \times R_+ \rightarrow R$ be a multiplier function having second partial derivatives with respect to the first argument, such that

- (v) for any $\alpha > 0$ $\phi_1(0, \eta, \alpha) = \eta$ for every $\eta \in R$
- (vi) for each fixed $\eta \in R$ $\phi_{11}(0, \eta, \alpha) \rightarrow \infty$ as $\alpha \rightarrow \infty$.

¹ R_+^k denotes the nonnegative orthant of R^k .

Examples of the λ functions are

$$M1: \quad \eta(\xi+1)^{1+\alpha}/(1+\alpha), \quad \alpha \text{ an even integer}$$

$$M2: \quad (\eta/\alpha)\exp(\alpha\xi)$$

$$M3: \quad \begin{cases} -\eta/4\alpha, & \xi \leq -1/2\alpha \\ \eta\alpha\xi^2 + \eta\xi, & \xi > -1/2\alpha \end{cases}$$

$$M4: \quad \begin{cases} -\eta^2/4\alpha, & \xi \leq -\eta/2\alpha \\ \alpha\xi^2 + \eta\xi, & \xi > -\eta/2\alpha. \end{cases}$$

An example of the ϕ function is

$$M5: \quad \alpha\xi^2 + \eta\xi.$$

Now define the modified Lagrangian function $P: \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}^p \times \mathbb{R}_+ \rightarrow \mathbb{R}$ as follows:

$$P(x, \mu, \psi, \alpha) = f(x) - \sum_{i=1}^m \lambda(g_i(x), \mu_i, \alpha) - \sum_{j=1}^p \phi(h_j(x), \psi_j, \alpha).$$

If the multiplier functions are chosen as in M1 or M5 one obtains, respectively, the P functions studied by Arrow and Hurwicz [1] and by Arrow and Solow [2]. By the choice M2 one obtains the P function studied by Gould and Howe [4].

The following result, sometimes referred to as Finsler's Lemma, will be used (see Debreu [3], or the appendix to this paper):

Lemma: Let Q be a real $n \times n$ matrix and let L be a real $m \times n$ matrix. Suppose $z^T Q z < 0$ for every $z \neq 0$ such that $Lz = 0$. Then, for all α sufficiently large, $z^T [Q - \alpha L^T L] z < 0$ for all $z \neq 0$. That is, if Q is negative definite on the null space of L then for α sufficiently large $Q - \alpha L^T L$ is negative definite on the whole space.

Let $L(x, \mu, \psi) = f(x) - \langle \mu, g(x) \rangle - \langle \psi, h(x) \rangle$, which is the usual Lagrangian function.

The first result of this paper is the following.

Theorem 1: Suppose (x^*, μ^*, ψ^*) satisfy the second order sufficiency conditions for x^* to be an isolated local solution to (P) and suppose strict complementarity holds. That is, we assume

$$(a) \quad \nabla L(x^*, \mu^*, \psi^*) = 0$$

$$(b) \quad g_i(x^*) \leq 0, \quad i = 1, \dots, m$$

$$h_j(x^*) = 0, \quad j = 1, \dots, p$$

$$(c) \quad \mu_i^* \geq 0, \quad \mu_i^* > 0 \text{ if and only if } g_i(x^*) = 0, \quad i = 1, \dots, m$$

$$(d) \quad y^T \nabla^2 L(x^*, \mu^*, \psi^*) y < 0 \text{ for every nonzero } y \text{ such that}$$

$$y^T \nabla g_i(x^*) = 0, \quad i \in I, \text{ and } y^T \nabla h_j(x^*) = 0, \quad j = 1, \dots, p, \text{ where } I$$

denotes the active inequality constraints. That is,

$I = \{i: g_i(x^*) = 0\}$. Then, if α is sufficiently large, the func-

tion $P(x, \mu^*, \psi^*, \alpha): \mathbb{R}^n \rightarrow \mathbb{R}$ has an unconstrained isolated local maximum at x^* .

Proof: For any $\alpha > 0$,

$$\begin{aligned} \nabla P(x^*, \mu^*, \psi^*, \alpha) &= \nabla f(x^*) - \sum_{i=1}^m \lambda_i(g_i(x^*), \mu_i^*, \alpha) \nabla g_i(x^*) \\ &\quad - \sum_{j=1}^p \phi_j(h_j(x^*), \psi_j, \alpha) \nabla h_j(x^*) \\ &= \nabla f(x^*) - \sum_I \mu_i^* \nabla g_i(x^*) - \sum_{j=1}^p \psi_j^* \nabla h_j(x^*) \\ &= \nabla L(x^*, \mu^*, \psi^*) = 0 \quad \text{by (a).} \end{aligned}$$

$$\begin{aligned} \nabla^2 P(x^*, \mu^*, \psi^*, \alpha) &= \nabla^2 f(x^*) - \sum_{i=1}^m [\lambda_i(g_i(x^*), \mu_i^*, \alpha) \nabla^2 g_i(x^*) \\ &\quad + \lambda_{11}(g_i(x^*), \mu_i^*, \alpha) \nabla g_i(x^*) \nabla^T g_i(x^*)] \\ &\quad - \sum_{j=1}^p [\phi_j(h_j(x^*), \psi_j^*, \alpha) \nabla^2 h_j(x^*) \end{aligned}$$

$$\begin{aligned}
& + \phi_{11}(h_j(x^*), \psi_j^*, \alpha) \nabla h_j(x^*) \nabla^T h_j(x^*)] \\
= & \nabla^2 L(x^*, \mu^*, \psi^*) - \sum_I \lambda_{11}(g_i(x^*), \mu_i^*, \alpha) \nabla g_i(x^*) \nabla^T g_i(x^*) \\
& - \sum_{j=1}^p \phi_{11}(h_j(x^*), \psi_j^*, \alpha) \nabla h_j(x^*) \nabla^T h_j(x^*).
\end{aligned}$$

Defining $J^T = [\nabla g_i(x^*), \dots, i \in I, \nabla h_1(x^*), \dots, \nabla h_p(x^*)]$, note that $y^T \nabla^2 L(x^*, \mu^*, \psi^*) y < 0$ for every nonzero y such that $Jy = 0$, by (d). By Finsler's Lemma, $\nabla^2 L(x^*, \mu^*, \psi^*) - kJ^T J$ is negative definite for some scalar k sufficiently large. Now if α is sufficiently large we can obtain

$$\begin{aligned}
\lambda_{11}(g_i(x^*), \mu_i^*, \alpha) &> k && \text{each } i \in I \\
\phi_{11}(h_j(x^*), \psi_j^*, \alpha) &> k && \text{each } j = 1, \dots, p
\end{aligned}$$

whence

$$\begin{aligned}
\nabla^2 P(x^*, \mu^*, \psi^*, \alpha) &= \nabla^2 L(x^*, \mu^*, \psi^*) - kJ^T J \\
&+ \sum_I [k - \lambda_{11}(g_i(x^*), \mu_i^*, \alpha)] \nabla g_i(x^*) \nabla^T g_i(x^*) \\
&+ \sum_{j=1}^p [k - \phi_{11}(h_j(x^*), \psi_j^*, \alpha)] \nabla h_j(x^*) \nabla^T h_j(x^*)
\end{aligned}$$

which, for all α sufficiently large, is negative definite, since large α implies that each of the dyadic terms has a negative coefficient and is hence negative semidefinite. □

III. A LOCAL SADDLE POINT RESULT

To obtain the main result, it is necessary to impose the further assumptions

- (iv) if $\alpha > 0$, $\eta \geq 0$ then $\lambda(\xi, \eta, \alpha)$ is monotonically nondecreasing over $\xi \in (-\infty, 0]$.

It should be noted that condition (iv) is satisfied by the examples M1 thru M4.

Theorem 2: If the multiplier functions satisfy properties (i)-(vi), then under the conditions of Theorem 1, if α is sufficiently large,

$$\bar{P}(x, \mu^*, \psi^*, \alpha) \leq \bar{P}(x^*, \mu^*, \psi^*, \alpha) \leq \bar{P}(x^*, \mu, \psi, \alpha)$$

for every x in some neighborhood N of x^* and every point $(\mu, \psi) \in \mathbb{R}_+^m \times \mathbb{R}^p$, where

$$\begin{aligned} \bar{P}(x, \mu, \psi, \alpha) = & f(x) + \sum_{i=1}^m [\lambda(0, \mu_i, \alpha) - \lambda(g_i(x), \mu_i, \alpha)] \\ & + \sum_{j=1}^p [\phi(0, \psi_j, \alpha) - \phi(h_j(x), \psi_j, \alpha)]. \end{aligned}$$

Proof: From Theorem 1, it follows immediately that $\bar{P}(x, \mu^*, \psi^*, \alpha) \leq \bar{P}(x^*, \mu^*, \psi^*, \alpha)$ for every x in some neighborhood N of x^* . Also, since $g_i(x^*) = 0$, $i \in I$, $h_j(x^*) = 0$, $j = 1, \dots, p$, we have

$$\bar{P}(x^*, \mu, \psi, \alpha) = f(x^*) + \sum_{i \notin I} [\lambda(0, \mu_i, \alpha) - \lambda(g_i(x^*), \mu_i, \alpha)].$$

For $i \notin I$, $\mu_i^* = 0$. Integration of (ii) from $g_i(x^*)$ to 0 shows that $\lambda(0, \mu_i^*, \alpha) - \lambda(g_i(x^*), \mu_i^*, \alpha) = 0$ for $i \notin I$. From the monotonicity property (iv), $\lambda(0, \mu_i, \alpha) - \lambda(g_i(x^*), \mu_i, \alpha) \geq 0$ for any $\mu_i \geq 0$. It follows immediately that $\bar{P}(x^*, \mu^*, \psi^*, \alpha) \leq \bar{P}(x^*, \mu, \psi, \alpha)$ for all $(\mu, \psi) \in \mathbb{R}_+^m \times \mathbb{R}^p$. □

APPENDIX

Lemma: If $z^T Q z < 0$ for every $z \neq 0$ such that $Lz = 0$ then $Q - \alpha L^T L$ is negative definite for α sufficiently large.

Proof: Let S^\perp denote the nullspace of L . Hence, $S^\perp = \{z: Lz=0\}$, $S = S^{\perp\perp}$. If $y \in S$, $y \neq 0$, then $y^T L^T L y = \|Ly\|^2 > 0$. Let $m_1 = \min_y [y^T L^T L y: y \in S, \|y\|=1]$, and let $M = \|Q\|$, the sup norm of the matrix Q . There are three cases to consider.

Case (i): Suppose $S^\perp = \mathbb{R}^n$. Then Q is negative definite and the result is true for all $\alpha \geq 0$ since $-L^T L$ is negative semidefinite.

Case (ii): Suppose $S^\perp = \{0\}$. Then $S = \mathbb{R}^n$. Then for every $v \in \mathbb{R}^n$, $v \neq 0$,

$$\begin{aligned} v^T [Q - \alpha L^T L] v &= v^T Q v - \alpha v^T L^T L v = v^T Q v - \alpha \left[\frac{v^T}{\|v\|} L^T L \frac{v}{\|v\|} \right] \|v\|^2 \\ &\leq \|v\|^2 M - \alpha m_1 \|v\|^2 = \|v\|^2 [M - \alpha m_1] < 0 \quad \text{if } \alpha > M/m_1. \end{aligned}$$

Case (iii): Suppose $\{0\} \neq S^\perp \subsetneq \mathbb{R}^n$. Then for every $z \in S^\perp$, $z \neq 0$, $z^T Q z < 0$. Hence, let $\max_z \{z^T Q z : z \in S^\perp, \|z\| = 1\} = -m_2 < 0$. Suppose $v \in \mathbb{R}^n$, $v \neq 0$. Then we can write $v = y + z$ for some $y \in S$, $z \in S^\perp$. Consequently,

$$\begin{aligned} v^T [Q - \alpha L^T L] v &= (y+z)^T [Q - \alpha L^T L] (y+z) \\ &= z^T Q z + y^T Q z + z^T Q y + y^T Q y - \alpha y^T L^T L y \\ &\leq -m_2 \|z\|^2 + 2M \|y\| \|z\| + M \|y\|^2 - \alpha m_1 \|y\|^2 \\ &= -\alpha m_1 \|y\|^2 - m_2 \left(\|z\| - \frac{M}{m_2} \|y\| \right)^2 + \frac{M^2}{m_2} \|y\|^2 + M \|y\|^2 \\ &= \|y\|^2 \left(-\alpha m_1 + \frac{M^2}{m_2} + M \right) - m_2 \left(\|z\| - \frac{M}{m_2} \|y\| \right)^2 \\ &< 0 \quad \text{if } \alpha > M/m_1 (1 + M/m_2). \end{aligned}$$

□

REFERENCES

- [1] K.J. Arrow and L. Hurwicz, Reduction of constrained maxima to saddle-point problems, in: Third Berkeley Symposium on Mathematical Statistics and Probability, ed. J. Neyman (University of California Press, Berkeley, 1956).
- [2] K.J. Arrow and R.M. Solow, Gradient methods for constrained maxima, with weakened assumptions, in: Studies in Linear and Non-linear Programming, ed. K. Arrow, L. Hurwicz, H. Uzawa (Stanford University Press, Stanford, 1958).
- [3] G. Debreu, Definite and semidefinite quadratic forms, *Econometrica* XX, (1952) 295-300.
- [4] F.J. Gould and S.M. Howe, "A new result on interpreting Lagrange multipliers as dual variables", Institute of Statistics Mimeo Series No. 738, Dept. of Statistics, University of North Carolina (Chapel Hill), January, 1971.